



### **Acknowledgements**

This talk highlights material captured in the draft NASA FM Handbook NASA-HDBK-1002. The following persons coauthored the FM Handbook:

Timothy Barth - NASA KSC and NESC SE Office; Micah Clark, John Day, Lorraine Fesq, Eric Rice - Jet Propulsion Laboratory, California Institute of Technology; Kristen Fretz - Johns Hopkins University, Applied Physics Laboratory; Kenneth Friberg - Friberg Autonomy (JPL Affiliate); Stephen Johnson - NASA Marshall Space Flight Center (MSFC) and University of Colorado, Colorado Springs; Philip Hattis, John West, Jeffrey Zinchuk - Draper Laboratory; David McComas - NASA GSFC; Marilyn Newhouse - Computer Science Corporation (MSFC Affiliate); Kevin Melcher - NASA GRC

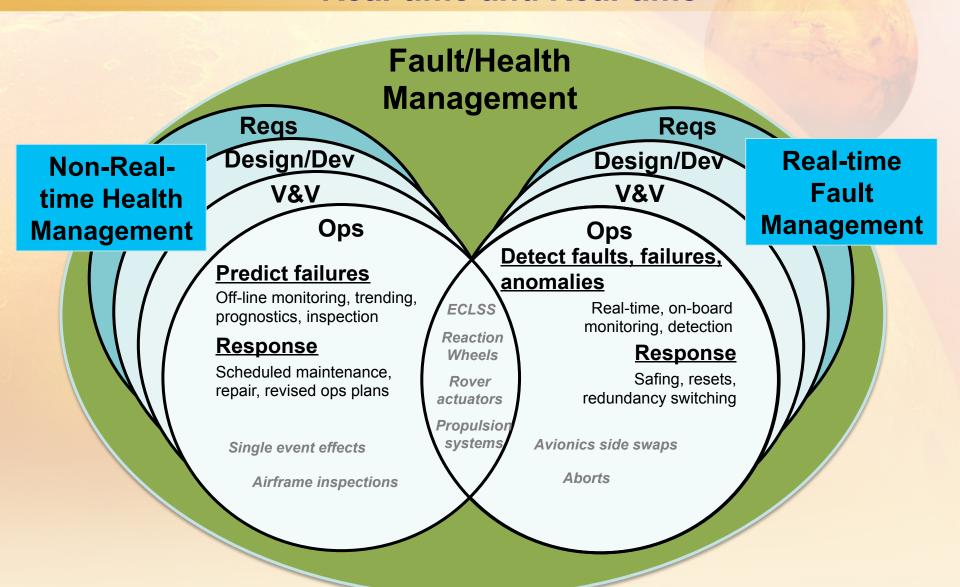


## **Agenda**

- A view of Health Management (HM) and Fault Management (FM)
- Robotic missions
- Shuttle and International Space Station (ISS)
- Changes in human rating requirements
- Ultimate challenge: Human exploration of Mars
- Summary and Recommendations



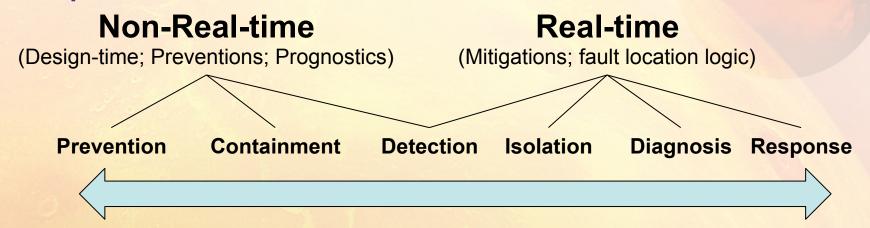
## At NASA, "Health Management" consists of Non-Real-time and Real-time



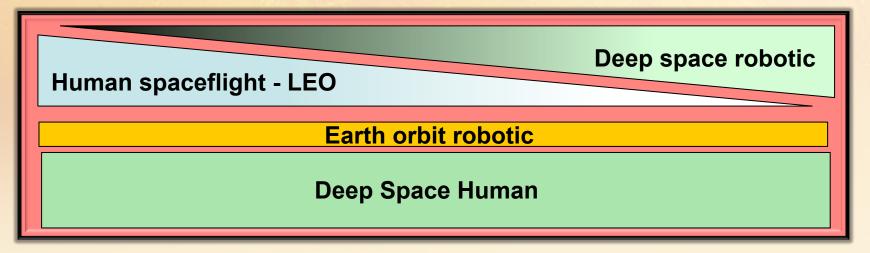


## **Spectrum of Health/Fault Management**

A spectrum of issues/options affect HM/FM scope and implementation



Mission characteristics determine emphasis and level of automation





# HM/FM is an engineering discipline with interfaces to Reliability/Maintainability (RM) and Safety

#### **Engineering**

Develop, verify and validate system designs, based on requirements

Redundancy, FM, prognostics, abort, situational awareness

Reliability requirements, failure modes & effects

Hazards, FT requirements

Design

Controls

#### RM

Define reliability requirements; assess system reliability

- Failure Modes/Effects
  - Critical Item Lists
  - Probabilistic RiskAssessment

Hazards, FT requirements

Reliability requirements, Fault analyses

#### Safety

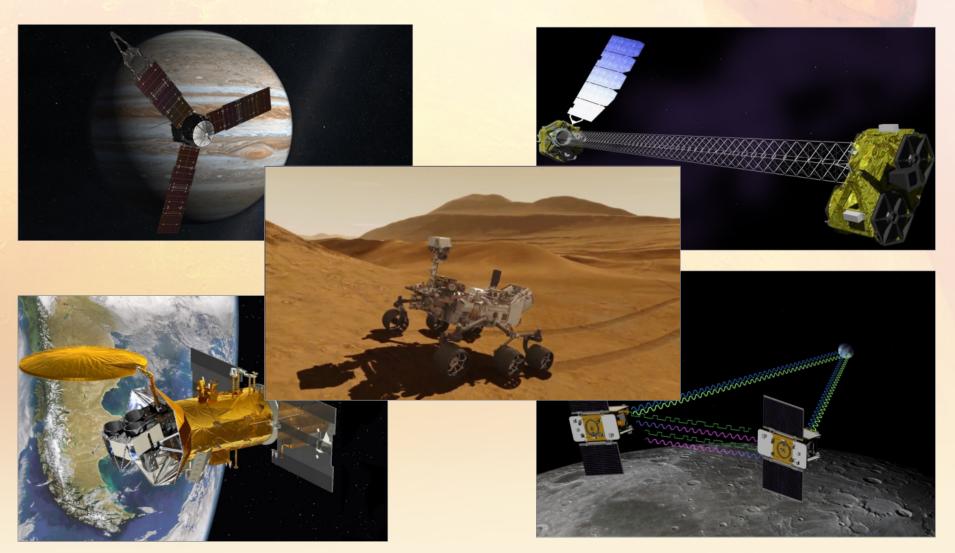
Define failure tolerance requirements, assess system hazards, assess identified controls

- Fault Tree Analyses
- Integrated Hazards
  - LOC/LOM



### **Robotic Missions**

HM is primarily FM with some monitoring/trending of limited life elements



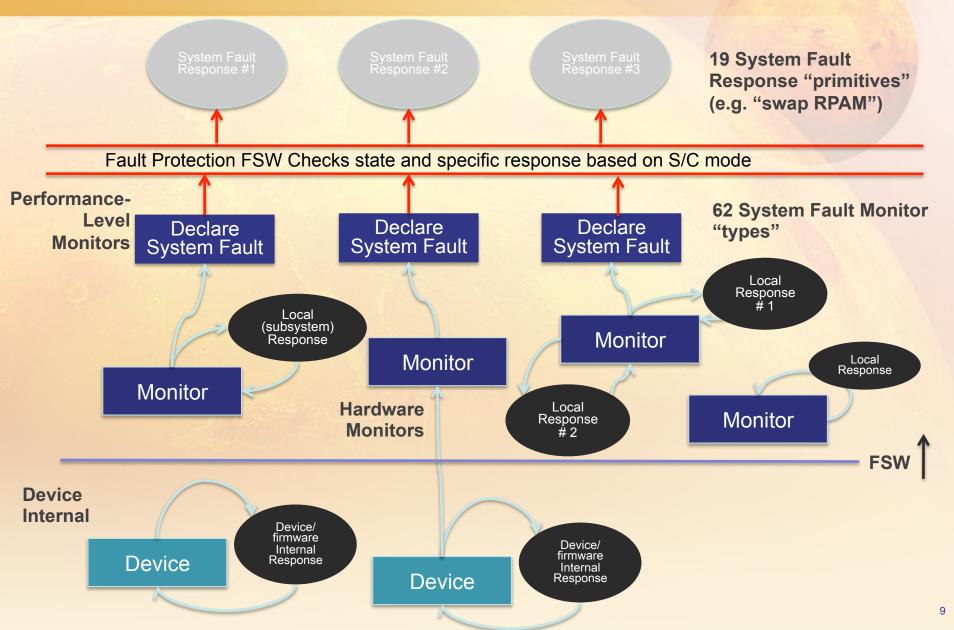


## **Robotic Mission Fault Management Features**

- Every science mission's flight system requires a degree of FM autonomy
  - Earth orbiters feature early critical events, short communication latencies and frequent communication opportunities which allow most FM functions to be performed on Earth by human operators and advisory systems
  - Deep space missions, have unique critical events (orbit insertions, entry/ descent/landing), long light-time delays, Deep Space Network (DSN) constraints, system resource constraints (e.g., battery state of charge) which preclude human operator intervention, and thus dictate extensive FM autonomy
  - All flight systems require FM that can contain the effects of failures and preserve functionality critical to keeping the system safe until operators can respond
- System complexity drives FM complexity including the following characteristics:
  - Structural complexity (e.g., the number of interconnected components)
  - Behavioral complexity (e.g., the variety of behaviors required)
  - Distributed complexity (e.g., the coordinated control of physically decoupled assets such as in formation flying and swarm missions)
  - Operational complexity (e.g., reliance on interactions between disparate systems and teams)



### **MSL On-Board Fault Protection Overview**





## **Robotic Mission HM/FM Design Environment**

#### Limited hardware redundancy

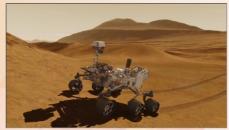
- Development costs of space systems are strongly coupled to system mass.
   Given cost and mass constraints, science missions often employ functional and informational redundancies instead of hardware-identical redundancy.
- Single string (no redundancy at all) is no longer uncommon (e.g. Mars Pathfinder, MERs, SMAP)

#### High reliability and long lifetime

- Overall reliability is driven by operational lifetimes of many years (e.g. Cassini nominal mission 11 years)
- Design for harsh operating environments including launch dynamics, low pressure/vacuum, high radiation, and extreme temperature and fluctuations/ cycles
- Attaining the required reliability over a mission's lifetime is usually achieved by conservatism in component selection (e.g. heritage, high reliability parts), design margins (e.g. temperature) and extensive testing



## **Mars Science Laboratory FM by Phase**

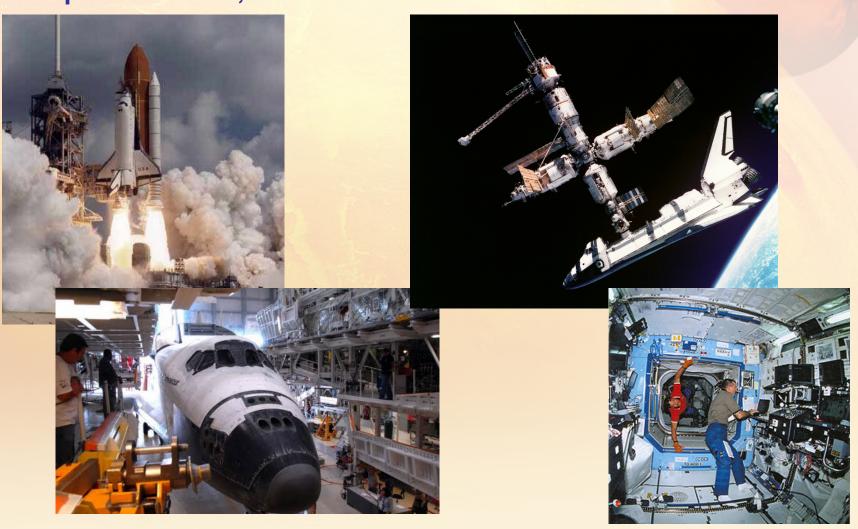


- Launch/Cruise/Approach (8.5 months)
  - Single fault tolerant and preserves the spacecraft in a power-thermal-comm-safe (& consumables) state for up to 2 weeks
  - Autonomous support for computer reset recovery provided for cruise operations
  - "Prime string" redundancy configuration to be used during EDL, which is "selected" in late cruise.
- EDL (EDL mode change ~20 days out, EDL event ~7 minutes)
  - EDL phase (starting several days prior to cruise stage separation) is single string and is NOT be single fault tolerant.
  - No autonomous support for computer reset recovery provided for EDL.
  - Computer reset recovery prior to start of entry managed by the Ops Team.
  - Effort to implement additional back-up capability is underway and is expected to be in place for EDL
- Surface (One Mars year, two Earth years)
  - Single fault tolerant and preserves the spacecraft in a power-thermal-comm-safe (& consumables) state indefinitely
  - Autonomous support for computer reset recovery provided for surface operations
  - After an on-board fault no support for autonomous resumption of normal sequence operations
  - Greatest current challenge is in the Sample Acquisition and Processing/Handling system



## **Shuttle and International Space Station (ISS)**

HM emphasis is on maintenance, inspection/repair, analysis of operational life, with limited instrumentation for health monitoring





## **New Human Rating Requirements**

- In 2007 the core requirement for redundancy for human rating was changed. Up to that point the basic requirement for redundancy was for two failure tolerance against catastrophic events.
- New requirements were driven by the need to provide the safest possible vehicle(s) while recognizing that for systems designed to go beyond LEO, the impact of imposing a blind two failure tolerance requirement would significantly impact the limited technical resources of mass, volume, and power.
- Efforts involving engineering, safety and mission assurance, and the crew office resulted in the following new core requirement:

The space system shall provide failure tolerance to catastrophic events, with the specific level of failure tolerance (1, 2 or more) and implementation (similar or dissimilar redundancy) derived from an integrated design and safety analysis.



## **Impact of New Human Rating Requirement**

- The emphasis is on the overall system capabilities utilizing similar systems, dissimilar systems, cross-strapping, and/or functional interrelationships that "ensure minimally acceptable system performance despite failures."
- Redundancy does not, by itself, make a system safe, it is the responsibility of the engineering and safety teams to determine the safest possible system design given the mission requirements and constraints.
- The culture of human systems engineering believes in common mode failures (based on experience from Shuttle), more than the robotic community and therefore often try to implement dissimilar redundancy.
- It is also highly desirable that the space flight system performance degrades in a predictable fashion to allow sufficient time for failure detection and, when possible, system recovery even when experiencing multiple failures.



## **Fault Management Requirements**

- The following are high level definitions and guidance for design of human-rated spacecraft. Finding the best allocation of FM functionality between automated (no human involvement), autonomous (no crew but ground engagement) and the crew is a major challenge.
  - 1) The space system shall provide the capability to detect and annunciate faults that affect critical systems, subsystems, and/or crew health.

    Rationale: A fault is defined as an undesired system state. A failure is an actual malfunction of a hardware item's intended function. It is necessary to alert the crew to faults (not just failures) that affect critical functions.
  - 2) The space system shall provide the capability to isolate and recover from faults that would result in a catastrophic event or an abort. Rationale: The intent is to provide isolation and recovery from faults where the system design (e.g. redundant strings or system isolation) enables the implementation of this capability.
  - 3) The crewed space system shall provide the capability for the crew to manually override higher level software control / automation (such as configuration change and mode change) when the transition to manual control of the system will not cause a catastrophic event.



## Mars Design Reference Architecture 5.0 Low-Earth Orbit Operations Challenges

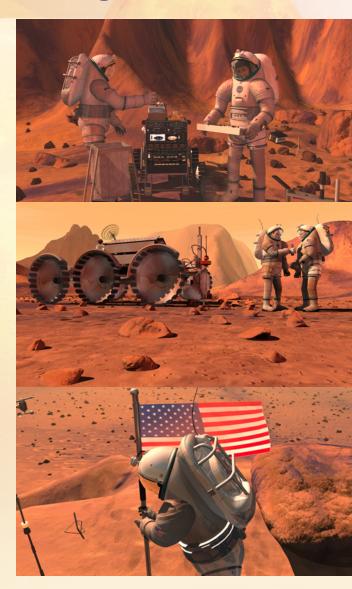


- Maintenance of vehicles in low-Earth orbit (LEO) for extended durations (300-390 days) to accommodate launch campaign
  - 7+ Earth-to-Orbit launches per mission
- Long-term system maintenance (micrometeoroid / orbital debris and cryogenic fluid management)
- Automated Rendezvous and Docking (AR&D) of large elements in LEO to minimize inspace assembly by crew
- Failure-tolerant launch/docking sequence to achieve <10% Loss of Mission
- Common thread: highly dependable avionics and software



## Mars Design Reference Architecture 5.0 Autonomous Operations Challenges

- Advanced autonomous capabilities are required due to long communications latency, lack of routine resupply
  - Identification of system failure modes
  - Model Based Reasoning techniques
  - Software verification and validation
  - Fault detection and reconfiguration
  - Trends identification and predictions
  - Lowest level component repair





## **Summary**

- Managing faults/failures is crucial to successful design, development and ops of NASA's crewed and robotic air and space systems
- The engineering "discipline" of health/fault management is not widely recognized nor evenly practiced across NASA
- Coalescing the HM/FM field
  - OCE/SMD-sponsored NASA FM Handbook NASA-HDBK-1002
  - OCE formed a NASA FM Community of Practice on NEN: <u>https://nen.nasa.gov/web/faultmanagement</u>
  - SMD sponsoring NASA FM Workshop April 10-12, 2012: http://icpi.nasaprs.com/NASAFMWorkshop



### Recommendations

- HM/FM is an important part of human and robotic spaceflight and is particularly critical for long duration spaceflight, especially with humans beyond low earth orbit
- System architects, stakeholders and designers need to become more aware of and conversant in the issues, design options, V&V and operations of HM/FM throughout the program/project lifecycle
  - Need to incorporate HM/FM based on needs, cost and risk
  - Balance/optimize automation vs human-in-the-loop (in space and on the ground)
  - Develop and deliver highly dependable avionics and software across all systems
- There is potential for collaboration and mutual benefit across the aerospace industry through working together in HM/FM but we need to understand much better, from our respective points of view and mission contexts, this discipline, its drivers, benefits and limitations